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## HI-8596 3.3V ARINC Line Driver Demonstration Board

## 1. INTRODUCTION

The HI-8596 Demonstration Board allows the user to evaluate the different modes of operation of the HI-8596 ARINC 429 line driver.
The HI-8596 includes a dual polarity voltage doubler, allowing it to operate from a single +3.3 V supply using four external capacitors. The part also features high-impedance outputs (tri-state) when both data inputs are taken high, allowing multiple line drivers to be connected to a common bus.

## 2. DEMONSTRATION BOARD

The demonstration board can generate patterns that drive the HI-8596 in various different ways through a set of 3 switches. The table below describes how to generate signals in high or low speed, in static states of ARINC 429 One, Zero or Null or to hold the outputs in tri-state. With only a single +3.3 V source the $\mathrm{HI}-8596$ will generate the rail voltages which are used to produce ARINC 429 specified signals.
The HI-8596 Demonstration Board has test points to measure the +/-VDD2 generated supplies, the TXA/B outputs, along with the alternative AMPA/B outputs and a trigger signal for oscilloscope viewing. If an alternative input source to the TX0/TX1 pins is desired, jumpers 1 and 2 can be opened from the available pattern generator and a user designed generator may bypass that on the Demonstration Board.



| Value | Part Number | Manufacturer |
| :--- | :--- | :--- |
| $0.1 \mu \mathrm{~F}$ | C0805C104M5UACTU | Kemet |
| $47 \mu \mathrm{~F}$ | EMK325B7476MM-T | Taiyo Yuden |
| $4.7 \mu \mathrm{~F}$ | LMK212B7475KG-T | Taiyo Yuden |

ESR: Fly cap < 0.5 ; Hold cap < $0.25 \Omega$.
Material: Ceramic or Tantalum, preferably multilayer. No polarized capacitors
Dielectric: XR7
Rated voltage: $\geq 10 \mathrm{~V}$

| Switch 1 | Switch 2 | Switch 3 | Tx Outputs | Slope |
| :---: | :---: | :---: | :---: | :---: |
| High | Run | X | Dynamic high speed (see below) | $1.5 \mu \mathrm{~s}$ |
| Low | Run | X | Dynamic low speed | $10 \mu \mathrm{~s}$ |
| X | Null | X | TXA $=0 \mathrm{~V}, \mathrm{TXB}=0 \mathrm{~V}$ | $\mathrm{n} / \mathrm{a}$ |
| X | Static | One | TXA $=+5 \mathrm{~V}, \mathrm{TXB}=-5 \mathrm{~V}$ | $\mathrm{n} / \mathrm{a}$ |
| X | Static | Zero | TXA $=-5 \mathrm{~V}, \mathrm{TXB}=+5 \mathrm{~V}$ | $\mathrm{n} / \mathrm{a}$ |
| X | Static | Hi-Z | TXA $=$ TXB $=\mathrm{Hi}-\mathrm{Z}$ | $\mathrm{n} / \mathrm{a}$ |



